CLAIMS:

- 1. A digital receiver for use in radar systems, comprising:
- an intermediate frequency (IF) converter to translate a higher frequency 1st IF to a lower frequency 2nd IF;
- 4 an analog-to-digital converter (ADC);
 - a digital signal processor (DSP) including IF (range) domain and Doppler (azimuth)
- 6 domain filtering, and
 - at least one phase history data interface;
- wherein the IF converter translates a given radar 1st IF frequency to a 2nd IF necessary to facilitate sampling and efficient quadrature demodulation, and at least one phase history output interface moves data to an image formation processor or a raw phase history storage subsystem.
 - 2. The invention of claim 1 wherein an out-of-band noise source provides a dither signal to the ADC to cause randomization of the ADC quantization error to thereby enhance the signal-to-noise ratio (SNR).
 - 3. The invention of claim 2 wherein the noise is formed in a manner so that its spectrum does not overlap the desired signal, allowing its subsequent removal by filtering.
 - 4. The invention of claim 3 wherein the noise introduced by the out-of-band noise source is removed to improve the radar receiver signal to noise ratio (SNR).

- 5. The invention of claim 1 wherein said second IF frequency is one fourth of the ADC sample frequency.
- 6. The invention of claim 5 wherein a quadrature demodulator and 1st-stage IF filter converts the sampled 2nd IF at the output of the ADC to base-band quadrature outputs (I and Q).
- 7. The invention of claim 5 further comprising a programmable data generator at the output of the ADC that provides a test signal to excite the DSP chain without the introduction of the analog IF input.
- 8. The invention of claim 6 further comprising a range pane filter connected to said quadrature outputs and having an IF filter with digitally selectable IF bandwidth.
- 9. The invention of claim 8 further comprising
- a high-pass filter at the output of said pane filter for removal of residual DC (zero frequency) at the output of the quadrature demodulator;
- a $0/\pi$ demodulator at the output of said high-pass filter for removing spurious modulation introduced by a radar exciter; and
- a vector presummer connected to said $0/\pi$ demodulator for adding multiple input vectors to produce a single output vector (azimuth sample).

- 10. The invention of claim 9 further comprising an azimuth prefilter (APF) with digitally selectable Doppler bandwidth connected to said presummer to filter presumed output vectors in the azimuth sample or Doppler domain.
- 11. The invention of claim 10 further comprising a 2nd range pane filter stage with digitally selectable bandwidth connected to said prefilter for further filtering and decimating each range vector.
- 12. The invention of claim 8 wherein a said IF filter has a multitude of IF bandwidths that are selectable to maximize the radar pulse width, thus maximizing the radar SNR versus radar operating range.
- 13. The invention of claims 8 wherein said IF filter has reprogrammable coefficients.
- 14. The invention of claim 1 wherein two phase history output interfaces are provided.
- 15. The invention of claim 14 wherein one of the phase history outputs provides raw presummed phase histories destined for a data recording system.
- 16. The invention of claim 15 wherein one of the phase history outputs provides range and Doppler pre-filtered and decimated data via a switch-fabric interface to a real-time image formation processor.

- 17. The invention of claim 16 wherein an out-of-band noise source provides a dither signal to the ADC to cause randomization of the ADC quantization error to thereby enhance the signal-to-noise ratio (SNR).
- 18. The invention of claim 17 wherein the noise is formed in a manner so that its spectrum does not overlap the desired signal, allowing its subsequent removal by filtering.
- 19. The invention of claim 18 wherein the noise introduced by the out-of-band noise source is removed to improve the radar receiver signal to noise ratio (SNR).
- 20. The invention of claim 1 wherein the first IF is at about 4GHz and the second IF frequency is at about 250 MHz.